Thermal Exchanges Evolvement of Electric Arcs in High Voltage Circuit Breakers

A. ZIANI¹, H. MOULAI¹
¹Laboratory of Electrical and Industrial Systems, FEI, USTHB, BP 32 Bab Ezzouar, Algiers, Algeria. Fax (213)26.621.13.41 Email: ziani08@yahoo.fr, moulaih@yahoo.fr

Abstract—This work is devoted to the study of the energy balance at the opening of an SF6 circuit breaker. A new model is proposed to simulate the thermal exchanges involved around the current zero as a function of time. The theoretical bases of this model consist in the coupling of electric and thermal equations of arc plasma. They take into account all the forms of energy that are susceptible to be implicated. It is especially focused on the energy radiated by the arc and its comparison with the other forms of energy. The obtained results are found in good agreement with measurements performed by other authors.

Keywords: Electric arc, thermal plasma, radiation, SF6 breaker

1. INTRODUCTION

SF6 circuit breakers are the most used for voltages ranging between 245kV and 1000kV thanks to their noteworthy physicochemical properties [1] and numerous works are devoted to this subject [2-4]. However, the energetic aspect of the thermal plasma within these breakers remains a primordial phenomenon for the survey of breaking processes. Thermal studies in SF6 present the electric arc as being formed by dissociated SF6 plasma of cylindrical geometry [1], constituted from a core at very elevated temperature and surrounded by a gas sheath more cold and of insulating nature (figure 1). The core and the sheath are separated by a plateau of temperature equal to 2000K [1] (temperature of SF6 dissociation).

Most 0D models of circuit breaker arcs, such as those proposed by Cassie [5] and Mayr [2], are based on this symmetrical representation in order to explain the disappearance of the plasma conductance and to link it to the disappearance of the core, because, in the case of SF6, only the core is assumed to be conductor [1] (the sheath is constituted from molecular gases).

At the opening of the circuit breaker and around zero of an alternative current, very important thermal exchanges between the sheath and the core will be established in order to enable the arc quenching and its cooling. The speed of these transfers determines the success or no of the breaking.

In order to follow the evolvement of these exchanges during the breaking period, we first developed a 0D arc model that integrates a dissipative term related to the thermal radiance, which is reported as the dominating phenomenon in plasmas of high current circuit breakers [6]. On the other hand, by a coupling between the proposed model and thermal transfer equations, we will study the variations of the arc conductance and the thermal transfers in SF6 arc plasma as a function of the deionisation constant of time. Three values of this constant will be taken from the literature [3, 7].
For this effect, the equations of the heat will be developed, and the influence of each term on the progress of the quenching will be described, and an energetic balance within the plasma will be proposed. The mathematical bases of the new model will be then established as well as the coupling between the different energetic components. Therefore, a new arc equation and the heat equation will be coupled with expressions of the three thermal transfer modes (convection, conduction and radiation) to obtain a system of 5 differential equations that will be solved numerically by Runge Kutta method for a default current of 90% of the interrupting capacity in an SF6 circuit breaker (245kV/50kA/50Hz).

Figure 1. Thermal structure of an arc in SF6

2. THERMAL SUCCESS OF THE BREAKING

The thermal plasma loses energy and cools according to the three modes of thermal transfer: convection, conduction and radiation. These 3 terms are found again in the heat equation [8,11] that can be written:

$$\text{div}(K_T \nabla T) + P_{\text{Ray}} + \rho c_p \frac{\partial T}{\partial t} = P + h(T_{\text{ex}} - T)$$

(1)

Where $K_T$ is the thermal conductivity, $T$ the temperature, $P_{\text{Ray}}$ the power lost by radiation, $\rho$ the density, $c_p$ the specific heat at constant pressure and $h$ the coefficient of thermal exchange.

$P$ represents the source term of the equation and corresponds to the power dissipated by Joule effect as a consequence of the current flow through the core of the plasma. Equation (1) shows that to avoid the thermal failure ($\frac{\partial T}{\partial t}$-negative) and to succeed the breaking, it is necessary that the dissipated power $P$ in the sheath remains lower than the sum of the three powers involved in the cooling. The breaking success depends therefore, in part, on the speed with which these three heights are going to evolve. If the energy provided by the arc as Joule effect overtakes the cooling energy, we will be in the case of a thermal excitement that is going to be followed by the breaking of the dielectric strength of the gas (SF6).

3. ENERGIC BALANCE OF THE ARC AT THE OPENING OF A CIRCUIT BREAKER

At the opening of the contacts, an electric arc will appear and generate an arc voltage $u_{\text{arc}}$ that will condition the energy dissipated by Joule effect in the circuit breaker, implying thus a very high increase of temperature. One will note it $W_1$. It is given by relation (2):

$$W_1 = \int_{t_0}^{t_f} i u_{\text{arc}} dt$$

(2)

Where $i$ is the current in the arc column, $t_0$ and $t_f$ are respectively the times of the beginning and the end of the breaking. The differential formulation is well adapted to determine these variations. Thus, equation (2) becomes:

$$dW_1 = i^2 u_{\text{arc}} dt$$

Since $u_{\text{arc}} = \frac{i}{g}$; where $g$ is the conductance of the arc. One can write therefore:

$$dW_1 = \frac{i^2}{g} dt$$

The determination of this variable returns therefore to solve numerically a differential equation system. One of the three modes of thermal transfer responsible on the heat evacuation is the cooling by conduction. Since plasma loses spontaneously the energy consequently to the existence of a temperature gradient $\nabla T$. The conduction thermal power can be expressed by:

$$P_c = -\nabla \cdot (K_T \nabla T)$$

(3)

Where $K_T$ is the thermal conductivity of the plasma.

The curve of the thermal conductivity in SF6 as a function of temperature shows the existence of a pick at a temperature $T=2.10^3 K$ [6].

Transfer by convection is the second mode by which plasma dissipates the heat. This mode is more efficient than thermal exchange by
conduction. The expression of the energy $dW_2$ evacuated during an elementary interval of time $dt$ is given by:

$$dW_2 = h(T_0 - T)dt$$  \hspace{0.5cm} (4)

Where $h$ is the coefficient of thermal exchange.

The convection power transferred by surface unit is then: $W_2 = h(T_0 - T)$.

For a forced convection, $h$ is estimated experimentally. For SF6, Xiang Zhang et al. [4] use a value of $h$ closer to the one of air. It is equal to 10.

The third mode by which the arc dissipates energy is the thermal transfer by radiation. Plasma exchanges heat with the outside medium by electromagnetic radiance. The wave length of the spectrum emitted by an arc plasma is much extended, but the spectral zone responsible of the energy transfer is located between 50nm and 10µm [8].

The total power $P_R$ radiated by the plasma in the entire spectral band, at a temperature $T$, is given by Stéfan –Boltzman’s equation:

$$P_R = \varepsilon \sigma (T^4 - T_0^4)$$

Where $\varepsilon$ is the plasma emissivity and $\sigma$ the coefficient of Stéfan - Boltzman.

We can therefore determine the energy $dW_3$ radiated per surface unit by the plasma during an elementary time $dt$:

$$dW_3 = -\varepsilon \sigma (T^4 - T_0^4)dt$$  \hspace{0.5cm} (5)

This equation will be also integrated in a differential equation system to be solved numerically.

4. EQUATIONS OF ARC MODELISATION

Equations of arc models generally describe the variations of the arc conductance as a function of the arc voltage $u(t)$ and its current $i(t)$.

Most models of arc use the principle that the conductance is a function of the energy $w$ contained in this arc: $g = f(w)$, where $w$ represents the difference between the energy provided by Joule effect and the energy evacuated towards the outside medium. For high currents, the quenching phase is well described by Cassie’s model; and for weak currents, Mayr’s model is the more appropriate [3].


This model has been established on the basis that the section of the arc remains constant during a thermal exchange by convection [5]. Two constants describe the differential equation: $\tau$ the constant of time of the electric arc that represents the time at the end of which the gas becomes again insulating, and $u_c$ the arc voltage.

$$\frac{d \ln g_1}{dt} = 1 \left( \frac{u^2}{u_c} - 1 \right)$$  \hspace{0.5cm} (6)

4.2. Mayr Model [2]

This model which is based on a thermal transfer by conduction is especially valid for currents lower than 100A [3]. The characteristic equation is:

$$\frac{d \ln g_2}{dt} = 1 \left( \frac{u_i}{p} - 1 \right)$$  \hspace{0.5cm} (7)

Where $\tau$ is the constant of time of the arc and $p$ the thermal power evacuated by the arc.

4.3. Proposed model

By inspiring from the model of Cassie, it is possible to study the part of each thermal transfer mode and the conditions of its preponderance with regard to others. This work is focused on the contribution of the thermal radiation in the cooling process and the electric arc quenching [9,11].

In most of circuit breaker models, authors generally suppose that the conductance of the arc expresses only as a function of the energy $Q$ used for its formation: $g = g(Q)$ [1, 5]. So, the total electric power provided to the arc can be written:

$$P = u_i i + \frac{dQ}{dt} + P_R$$  \hspace{0.5cm} (8)

$P$ : The total power provided to the arc

$P_p$ : The power lost by electric conduction

$P_R$ : The power lost by radiation

$\frac{dQ}{dt}$ : The necessary power to the creation of the arc

The derivative of the conductance with regard to time can be written as follows:
By replacing the term \( \frac{dQ}{dt} \) by its expression extracted from equation (8), one obtains:

\[
\frac{dg}{dt} = \frac{dg}{dQ} \cdot \frac{1}{g} (P - P_p - P_R) = \frac{dg}{dQ} \cdot P - \frac{dg}{dQ} \cdot g \cdot P_R
\]

(9)

The power provided to the arc is \( P = u(t) \) and the current through the arc is \( i(t) = u.g \).

The power lost by electric conduction is then:

\[
P_p = u_a^2 \cdot g.
\]

The conductance per length unit of an arc column can be expressed by: \( g = \frac{S}{\rho_r} \) where \( S \) is the surface of the arc column and \( \rho_r \) its resistivity. One can then express the section of the arc by the following expression: \( S = g \cdot \rho_r \).

By using the relations of proportionality already used by Cassie for the energy \( Q \) used to the arc creation and to the power \( P_p \) by electric conduction [5], one obtains:

\[
Q = S \cdot C \quad \text{and} \quad P_p = S \cdot \lambda \quad \text{where} \ C \quad \text{and} \ \lambda \quad \text{are constants of proportionality.}
\]

It comes therefore:

\[
\frac{dg}{dQ} = \frac{1}{\rho_r \cdot C}.
\]

By replacing this expression in equation (9), one obtains:

\[
\frac{dg}{dt.g} = \frac{1}{\rho C} \left( u^2 - u_a^2 - \frac{P_R}{g} \right)
\]

(10)

By putting \( u_a^2 \) in factor, we obtain:

\[
\frac{dg}{dt.g} = \frac{u_a^2}{\rho C} \left( u^2 - \frac{u_a^2}{g} - \frac{P_R}{u_a^2} \right)
\]

(11)

\[
P_p = S \lambda = u_a^2 \cdot g
\]

\[
u_a^2 = \frac{S \lambda}{g} = \rho_r \lambda.
\]

By replacing this value in relation (11):

\[
\frac{dg}{dt.g} = \frac{\rho \lambda}{\rho_C} \left( \frac{u^2}{u_a^2} - 1 - \frac{P_R}{g \cdot u_a^2} \right)
\]

After simplification and by setting: \( \lambda = \tau \) and \( g \cdot u_a^2 = P_p \)

One finally obtains:

\[
\frac{d \ln g}{dt} = \frac{1}{\tau} \left( \frac{u^2}{u_a^2} - 1 - \frac{P_R}{P_p} \right)
\]

(12)

This new differential equation describes well the arc quenching in high voltage circuit breakers for very high currents. The obtained results have been validated by comparison with those obtained experimentally by Schavemaker et al. [3].

5. COUPLING: EQUATION OF MODELISATION-ENERGIES

The equation obtained in the above model has been coupled with the equations of the heat, the thermal transfer by conduction, the power of radiation and the energy lost by Joule effect. We obtain then a system of 5 differential equations with 5 variables: \( g, T, W_1, W_2, \) and \( W_3 \):

\[
\begin{cases}
\frac{d \ln g}{dt} = \frac{1}{\tau} \left( \frac{u^2}{u_a^2} - 1 - \frac{\sigma \varepsilon \left(T^4 - T_0^4\right)}{g \cdot u_a^2} \right) \\
\rho \cdot \varepsilon \cdot \frac{\partial T}{\partial t} - \nabla \cdot (K \cdot \nabla (T)) = h(T_0 - T) + \frac{i^2}{g} - \sigma \varepsilon \left(T^4 - T_0^4\right) \\
\frac{dW_1}{dt} = h(T_0 - T) \\
\frac{dW_2}{dt} = -\sigma \varepsilon \left(T^4 - T_0^4\right) \\
\frac{dW_3}{dt} = \frac{i^2}{g}
\end{cases}
\]

\( T \): the temperature of the plasma in Kelvin

\( T_0 \): the external temperature
\[ \rho : \text{the density of the gas (SF6) in kg/m}^3 \]
\[ c : \text{the specific heat of the gas in J/kg/K} \]
\[ K_T : \text{the thermal conductivity of the gas in W/m/K} \]
\[ h : \text{the thermal exchange factor in W/K} \]
\[ W_i : \text{the energy provided by the arc.} \]

The necessary initial conditions to the numerical solving are as:
\[ W_1 = W_2 = W_3 = 0; T(0) = 15000 \text{ K}; g(0) = 10^4 \text{ S.m}^{-1}. \] The source element is the power emitted by the arc; it is expressed by:
\[ i^2/g. \] The principle of the coupling of the equation system is described on figure 2.

6. RESULTS AND DISCUSSIONS

The numerical solving of the arc equations in high voltage circuit breakers is executed using well adapted parameters: temperature between 10000K and 20000K [7] and duration of the simulation: between 0 and 90 microseconds in order to avoid the restoration of the Transient Recovery Voltage (TRV) [1].

![Fig. 2: Flow chart of coupling principle](image)

For this survey, the breaking is simulated for a default current at 90\% of the interrupting capacity for an SF6 breaker (245kV/50kA/50Hz). P. Schavemaker et al [3] and J. L. Guardado [7] have performed experimental works on the same apparatus. Runge-Kutta method has been used in order to solve numerically the system of 5 equations where the dielectric (SF6) intervenes in the calculations as an initial conductance which value is \( 10^4 \text{Sm}^{-1} \) at temperature \( T=15000\text{K} \). The value of the plasma emissivity has been calculated by [10]. The thermal exchange factor \( h \) is taken, in the case of a forced puffer circuit breaker, equal to 10. The SF6 density has been determined according to the works of D. Koch [6].

Current and arc voltage variations are represented on figure 3. One notes that this simulation produces an arc voltage of about 1.2kV, very lower than the nominal voltage of the breaker (245kV), what confirms the non limiting effect of current for this breaker [1]. The value of the overvoltage peak reaches 2.4kV at the end of breaking, and one notes that it is close to the experimental value.

Most of the works consecrated to arcing in high voltage breakers neglect the phenomenon of convection cooling with regard to conduction [1]. It as well as in this paper, the investigations will be focused on thermal convection effect. Figure 4 shows a very fast decrease of the arc conductance, with an average speed of about 100S/\( \mu \text{s} \) due to SF6 recovering of its dielectric properties for the three initial plasma temperatures: 20000, 15000 and 10000K.

The effect of temperature and therefore of radiation appears clearly and only before the first 20 microseconds. Figures 5, 6 and 7 are obtained for the three considered values of the deionisation constant [3, 7]: \( \tau_1 = 0.27 \mu \text{s}, \tau_2 = 0.57 \mu \text{s} \) and \( \tau_3 = 1.2 \mu \text{s} \). They, first of all, show that only the energy provided by Joule effect is influenced by the change of the value of the deionisation constant. One also notes that this Joule energy decreases with the constant \( \tau \). As it also appears on these figures that the energy due to thermal radiation becomes constant (\( P_R=0 \)) after the time \( t = 20 \mu \text{s} \). It can be explained by the disappearance of the arc core at this instant and the molecular gas apparition without thermal radiation effect.
**Figure 3:** Current and arc voltage evolution

**Figure 4:** Variations of the logarithm of the conductance ($S$) as a function of time.

**Figure 5:** Thermal transfer for $\tau = 0.27 \mu s$

**Figure 6:** Thermal transfer for $\tau = 0.57$ microseconds
7. CONCLUSION

In this work, a new 0D arc model integrating the effect of thermal radiation emitted by a plasma at the time of its cooling is developed. This model gave good results and permitted a better modeling of the arc breaking in high voltage circuit breakers for high intensity currents (extension of Cassie model). The obtained results are in good agreement with experimental works.

On the other hand, an original coupling of the model with thermal exchange expressions enabled, by a numeric approach, to study the evolution of the arc conductance as well as the influence of the deionisation time constant on the speed of thermal transfer evolution.

We showed that only the Joule energy provided by the arc is influenced by the variation of this parameter.

The disappearance of the radiated thermal power after the SF6 recovering of its dielectric state confirms the validation of the results obtained by the coupling of the model with the heat equation. It is verified for the three considered values of the deionisation constant.

References